Remote Control Manual

SDG Series
Function/Arbitrary
Waveform Generator
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1 Introduction of the SCPI Language

1.1 About Commands & Queries

This section lists and describes the remote control commands and queries recognized by the instrument. All commands and queries can be executed in either local or remote state.

Each command or query, with syntax and other information, has some examples listed. The commands are given in both long and short format at “COMMAND SYNTAX”, and the subject is indicated as a command or query or both. Queries perform actions such as obtaining information, and are recognized by the question mark (?) following the header.

1.1.1 How They are Listed

The descriptions are listed in alphabetical order according to their short format.

1.1.2 How They are Described

In the descriptions themselves, a brief explanation of the function performed is given. This is followed by a presentation of the formal syntax, with the header given in Upper-and-Lower-Case characters and the short form derived from it in ALL UPPER-CASE characters. Where applicable, the syntax of the query is given with the format of its response.

1.1.3 When can They be Used

The commands and queries listed here can be used for SDGxxxx Series Function/Arbitrary Waveform Generators.

1.1.4 Command Notation

The following notations are used in the commands:

< > Angular brackets enclose words that are used as placeholders, of which there are two types: the header path and the data parameter of a command.

:= A colon followed by an equals sign separates a placeholder, from the description of
the type and range of values that may be used in a command instead of the placeholder.

{} Braces enclose a list of choices, one of which must be made.

[ ] Square brackets enclose optional items.

… An ellipsis indicates that the items both to its left and right may be repeated for a number of times.

## 1.2 Table of Commands & Queries

<table>
<thead>
<tr>
<th>Short</th>
<th>Long Form</th>
<th>Subsystem</th>
<th>What Command/Query does</th>
</tr>
</thead>
<tbody>
<tr>
<td>*IDN</td>
<td>*IDN</td>
<td>SYSTEM</td>
<td>Gets identification from device.</td>
</tr>
<tr>
<td>*OPC</td>
<td>*OPC</td>
<td>SYSTEM</td>
<td>Gets or sets the OPC bit (0) in the Event Status Register (ESR).</td>
</tr>
<tr>
<td>*CLS</td>
<td>*CLS</td>
<td>SYSTEM</td>
<td>Clears all the status data registers.</td>
</tr>
<tr>
<td>*ESE</td>
<td>*ESE</td>
<td>SYSTEM</td>
<td>Sets or gets the Standard Event Status Enable register (ESE).</td>
</tr>
<tr>
<td>*ESR</td>
<td>*ESR</td>
<td>SYSTEM</td>
<td>Reads and clears the contents of the Event Status Register (ESR).</td>
</tr>
<tr>
<td>*RST</td>
<td>*RST</td>
<td>SYSTEM</td>
<td>Initiates a device reset.</td>
</tr>
<tr>
<td>*SRE</td>
<td>*SRE</td>
<td>SYSTEM</td>
<td>Sets the Service Request Enable register (SRE).</td>
</tr>
<tr>
<td>*STB</td>
<td>*STB</td>
<td>SYSTEM</td>
<td>Gets the contents of the IEEE 488.2 defined status register.</td>
</tr>
<tr>
<td>*TST</td>
<td>*TST</td>
<td>SYSTEM</td>
<td>Performs an internal self-test.</td>
</tr>
<tr>
<td>*WAI</td>
<td>*WAI</td>
<td>SYSTEM</td>
<td>Wait to continue command.</td>
</tr>
<tr>
<td>DDR</td>
<td>DDR</td>
<td>SYSTEM</td>
<td>Reads and clears the Device Dependent Register (DDR).</td>
</tr>
<tr>
<td>CMR</td>
<td>CMR</td>
<td>SYSTEM</td>
<td>Reads and clears the command error register.</td>
</tr>
<tr>
<td>CHDR</td>
<td>COMM_HEADER</td>
<td>SIGNAL</td>
<td>Sets or gets the command returned format</td>
</tr>
<tr>
<td>OUTP</td>
<td>OUTPUT</td>
<td>SIGNAL</td>
<td>Sets or gets output state.</td>
</tr>
<tr>
<td>BSWV</td>
<td>BASIC_WAVE</td>
<td>SIGNAL</td>
<td>Sets or gets basic wave parameters.</td>
</tr>
<tr>
<td>MDWV</td>
<td>MODULATEWAVE</td>
<td>SIGNAL</td>
<td>Sets or gets modulation parameters.</td>
</tr>
<tr>
<td>SWWV</td>
<td>SWEEPWAVE</td>
<td>SIGNAL</td>
<td>Sets or gets sweep parameters.</td>
</tr>
<tr>
<td>BTWV</td>
<td>BURSTWAVE</td>
<td>SIGNAL</td>
<td>Sets or gets burst parameters.</td>
</tr>
<tr>
<td>PACP</td>
<td>PARACOPY</td>
<td>SIGNAL</td>
<td>Copies parameters from one channel to the other.</td>
</tr>
<tr>
<td>ARWV</td>
<td>ARB_WAVE</td>
<td>DATA</td>
<td>Changes arbitrary wave type.</td>
</tr>
<tr>
<td>SYNC</td>
<td>SYNC</td>
<td>SIGNAL</td>
<td>Sets or gets synchronization signal.</td>
</tr>
<tr>
<td>NBFM</td>
<td>NUMBER_FORMAT</td>
<td>SYSTEM</td>
<td>Sets or gets data format.</td>
</tr>
<tr>
<td>LAGG</td>
<td>LANGUAGE</td>
<td>SYSTEM</td>
<td>Sets or gets language.</td>
</tr>
</tbody>
</table>
### IEEE 488.2 Common Command Introduction

IEEE standard defines the common commands used for querying the basic information of the instrument or executing basic operations. These commands usually start with "\*" and the length of the keywords of the command is usually 3 characters.

#### 1.3.1 IDN

**DESCRIPTION**

The \*IDN? query causes the instrument to identify itself. The response comprises manufacturer, model, serial number, software version and firmware version.

**QUERY SYNTAX**

\*IDN?
RESPONSE FORMAT

*IDN, <device id>,<model>,<serial number>,
<software version>, <firmware version>.

<device id>:="SDG" is used to identify instrument.
<model>:= A model identifier less than 14 characters, should not
contain the word "MODEL".
<serial number>: Each product has its own number, the serial
number can labeled product uniqueness.
<software version>: = A serial numbers about software version.
<firmware version>: The firmware level field, should contain
information about all separately revisable subsystems. This
information can be contained in single or multiple revision codes.

EXAMPLE

Reads version information.

*IDN?
Return:

*IDN SDG, SDG5162, 120465, 5.01.02.05, 02-00-00-21
-24(It may differ from each version)

Notes:

1) Parameter/command SDG800 SDG1000 SDG2000X SDG5000
   <firmware version> yes yes yes no

2) Explain for <firmware version>-value1- value2- value3- value4- value5.
   value1: PCB version.
   value2: Hardware version.
   value3: Hardware subversion.
   value4: FPGA version.
   value5: CPLD version.

1.3.2 OPC

DESCRIPTION

The *OPC (Operation Complete) command sets the OPC
bit (bit 0) in the standard Event Status Register (ESR).
This command has no other effect on the operation of the device
because the instrument starts parsing a command or query only
after it has completely processed the previous command or
query.

The *OPC? query always responds with the ASCII character 1
because the device only responds to the query when the
previous command has been entirely executed.

COMMAND SYNTAX

*OPC
1.3.3 CLS

DESCRIPTION
The *CLS command clears all the status data registers.

COMMAND SYNTAX
*CLS

EXAMPLE
The following command causes all the status data registers to be cleared:
*CLS

RELATED COMMANDS
CMR, DDR, *ESR, *STB

1.3.4 ESE

DESCRIPTION
The *ESE command sets the Standard Event Status Enable register (ESE). This command allows one or more events in the ESR register to be reflected in the ESB summary message bit (bit 5) of the STB register. The *ESE? query reads the contents of the ESE register.

COMMAND SYNTAX
*ESE <value>
[value] := 0 to 255.

QUERY SYNTAX
*ESE?

RESPONSE FORMAT
*ESE <value>

EXAMPLE
The following instruction allows the ESB bit to be set if a user request (URQ bit 6, i.e. decimal 64) and/or a device dependent error (DDE bit 3, i.e. decimal 8) occurs. Summing these values yields the ESE register mask 64+8=72.
*ESE?
Return:
1.3.5 ESR

**DESCRIPTION**
The *ESR? query reads and clears the contents of the Event Status Register (ESR). The response represents the sum of the binary values of the register bits 0 to 7.

**QUERY SYNTAX**
*ESR?

**RESPONSE FORMAT**
*ESR <value>
<value> := 0 to 255

**EXAMPLE**
The following instruction reads and clears the content of the ESR register:
*ESR?
Return:
*ESR 0

**RELATED COMMANDS**
*CLS, *ESE

1.3.6 RST

**DESCRIPTION**
The *RST command initiates a device reset. The *RST sets all of traces to the GND line and recalls the default setup.

**COMMAND SYNTAX**
* RST

**EXAMPLE**
This example resets the signal generator:
*RST

1.3.7 SRE

**DESCRIPTION**
The *SRE command sets the Service Request Enable register (SRE). This command allows the user to specify which summary message bit(s) in the STB register will generate a service request.
A summary message bit is enabled by writing a ‘1’ into the corresponding bit location. Conversely, writing a ‘0’ into a given bit location prevents the associated event from generating a service request (SRQ). Clearing the SRE register disables SRQ interrupts. The *SRE? query returns a value that, when converted to a binary number represents the bit settings of the SRE register. Note that bit 6 (MSS) cannot be set and it’s returned value is always zero.

**COMMAND SYNTAX**

*SRE <value>

<value> := 0 to 255

**QUERY SYNTAX**

*SRE?

**RESPONSE FORMAT**

*SRE <value>

**EXAMPLE**

The following instruction allows a SRQ to be generated as soon as the MAV summary bit (bit 4, i.e. decimal 16) or the INB summary bit (bit 0, i.e. decimal 1) in the STB register, or both are set. Summing these two values yields the SRE mask 16 + 1 = 17.

*SRE?

Return:

*SRE 17

### 1.3.8 STB

**DESCRIPTION**

The *STB? query reads the contents of the 488.2 defined status register (STB), and the Master Summary Status (MSS). The response represents the values of bits 0 to 5 and 7 of the Status Byte register and the MSS summary message. The response to a *STB? query is identical to the response of a serial poll except that the MSS summary message appears in bit 6 in place of the RQS message.

**QUERY SYNTAX**

*STB?

**RESPONSE FORMAT**

*STB <value>

<value> := 0 to 255

**EXAMPLE**

The following reads the status byte register:

*STB?

Return:
1.3.9 TST

DESCRIPTION

The *TST? query performs an internal self-test and the response indicates whether the self-test has detected any errors. The self-test includes testing the hardware of all channels, the time-base and the trigger circuits. Hardware failures are identified by a unique binary code in the returned <status> number. A “0” response indicates that no failures occurred.

QUERY SYNTAX

*TST?

RESPONSE FORMAT

*TST <status>

<status> : = 0 self-test successful

EXAMPLE

The following causes a self-test to be performed:

TST?

Return (if no failure):

*TST 0

RELATED COMMANDS

*CAL

Note:

<table>
<thead>
<tr>
<th>Parameter/command</th>
<th>SDG800</th>
<th>SDG1000</th>
<th>SDG2000X</th>
<th>SDG5000</th>
</tr>
</thead>
<tbody>
<tr>
<td>TST</td>
<td>no</td>
<td>yes</td>
<td>yes</td>
<td>yes</td>
</tr>
</tbody>
</table>

1.3.10 WAI

DESCRIPTION

The *WAI (WAIT to continue) command, requires by the IEEE 488.2 standard, has no effect on the instrument, as the signal generator only starts processing a command when the previous command has been entirely executed.

COMMAND SYNTAX

*WAI

RELATED COMMANDS

*OPC
1.3.11 DDR

DESCRIPTION

The DDR? query reads and clears the contents of the device dependent or device specific error register (DDR). In case of a hardware failure, the DDR register specifies the origin of the failure.

QUERY SYNTAX

DDR?

RESPONSE FORMAT

DDR <value>

[value] := 0 to 65535

EXAMPLE

DDR?

Return:

DDR 0

The following table gives details:

<table>
<thead>
<tr>
<th>Bit</th>
<th>Bit Value</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>15...14</td>
<td>Reserved</td>
<td></td>
</tr>
<tr>
<td>13</td>
<td>8192</td>
<td>Time-base hardware failure detected</td>
</tr>
<tr>
<td>12</td>
<td>4096</td>
<td>Trigger hardware failure detected</td>
</tr>
<tr>
<td>11</td>
<td>Reserved</td>
<td></td>
</tr>
<tr>
<td>10</td>
<td>Reserved</td>
<td></td>
</tr>
<tr>
<td>9</td>
<td>512</td>
<td>Channel 2 hardware failure detected</td>
</tr>
<tr>
<td>8</td>
<td>256</td>
<td>Channel 1 hardware failure detected</td>
</tr>
<tr>
<td>7</td>
<td>128</td>
<td>External input overload condition detected</td>
</tr>
<tr>
<td>6...4</td>
<td>Reserved</td>
<td></td>
</tr>
<tr>
<td>3</td>
<td>Reserved</td>
<td></td>
</tr>
<tr>
<td>2</td>
<td>Reserved</td>
<td></td>
</tr>
<tr>
<td>1</td>
<td>2</td>
<td>Channel 2 overload condition detected</td>
</tr>
<tr>
<td>0</td>
<td>1</td>
<td>Channel 1 overload condition detected</td>
</tr>
</tbody>
</table>

Notes:

<table>
<thead>
<tr>
<th>Parameter/command</th>
<th>SDG800</th>
<th>SDG1000</th>
<th>SDG2000X</th>
<th>SDG5000</th>
</tr>
</thead>
<tbody>
<tr>
<td>DDR</td>
<td>yes</td>
<td>yes</td>
<td>no</td>
<td>yes</td>
</tr>
</tbody>
</table>

1.3.12 CMR

DESCRIPTION

The CMR? query reads and clears the contents of the command error register (CMR). See the table below which specifies the last syntax error type detected by the instrument.

QUERY SYNTAX

CMR?
RESPONSE FORMAT
CMR <value>
[value] := 0 to 14

EXAMPLE
CMR?
Return:
CMR 0

<table>
<thead>
<tr>
<th>Value</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td></td>
</tr>
<tr>
<td>1</td>
<td>Unrecognized command/query header</td>
</tr>
<tr>
<td>2</td>
<td>Invalid character</td>
</tr>
<tr>
<td>3</td>
<td>Invalid separator</td>
</tr>
<tr>
<td>4</td>
<td>Missing parameter</td>
</tr>
<tr>
<td>5</td>
<td>Unrecognized keyword</td>
</tr>
<tr>
<td>6</td>
<td>String error</td>
</tr>
<tr>
<td>7</td>
<td>Parameter can’t allowed</td>
</tr>
<tr>
<td>8</td>
<td>Command String Too Long</td>
</tr>
<tr>
<td>9</td>
<td>Query cannot allowed</td>
</tr>
<tr>
<td>10</td>
<td>Missing Query mask</td>
</tr>
<tr>
<td>11</td>
<td>Invalid parameter</td>
</tr>
<tr>
<td>12</td>
<td>Parameter syntax error</td>
</tr>
<tr>
<td>13</td>
<td>Filename too long</td>
</tr>
<tr>
<td>14</td>
<td>Directory not exist</td>
</tr>
</tbody>
</table>

Note:
Parameter/command | SDG800 | SDG1000 | SDG2000X | SDG5000 |
-------------------|-------|--------|--------|--------|
CMR                | yes   | yes    | no     | yes    |

1.4 Comm_Header Command

DESCRIPTION
This command is used to change the query command returned format. "SHORT" parameter returns short format. "LONG" parameter returns long format. "OFF" returns nothing.

COMMAND SYNTAX
CHDR (Comm_HeaDeR) <parameter>
<parameter> := {SHORT, LONG, OFF}

QUERY SYNTAX
CHDR (Comm_HeaDeR)?

RESPONSE FORMAT
CHDR <parameter>
EXAMPLE

Set query command format to long.
CHDR LONG

Read query command format.
CHDR?
Return:
COMM_HEADER LONG

Note:
<table>
<thead>
<tr>
<th>Parameter/command</th>
<th>SDG800</th>
<th>SDG1000</th>
<th>SDG2000X</th>
<th>SDG5000</th>
</tr>
</thead>
<tbody>
<tr>
<td>CHDR</td>
<td>yes</td>
<td>yes</td>
<td>no</td>
<td>yes</td>
</tr>
</tbody>
</table>

1.5 Output Command

DESCRIPTION

Enable or disable the output of the [Output] connector at the front panel corresponding to the channel.
The query returns the output state, load and polarity parameters value.

COMMAND SYNTAX

<channel>:OUTP (OUTPut) <parameter>
<channel> := (C1, C2)
<parameter> := {a parameter from the table below}

<table>
<thead>
<tr>
<th>Parameters</th>
<th>Value</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>ON</td>
<td>---</td>
<td>Turn on</td>
</tr>
<tr>
<td>OFF</td>
<td>---</td>
<td>Turn off</td>
</tr>
<tr>
<td>LOAD</td>
<td>&lt;load&gt;</td>
<td>Value of load</td>
</tr>
<tr>
<td>PLRT</td>
<td>&lt;NOR, INVT&gt;</td>
<td>Value of polarity parameter</td>
</tr>
</tbody>
</table>

< load> := {please see the note below.}

QUERY SYNTAX

<channel>: OUTP(OUTPut)?

RESPONSE FORMAT

<channel>: OUTP <load>

EXAMPLE

Turn on channel one.
C1: OUTP ON

Read channel one output state.
C1: OUTP?
Return:
C1: OUTP ON, LOAD, HZ, PLRT, NOR
Set the load to 50.
C1: OUTP LOAD, 50

Set the load to HZ.
C1: OUTP LOAD, HZ

Set the polarity normal.
C1: OUTP PLRT, NOR

Set the polarity inverted.
C1: OUTP PLRT, INVT

Note:

<table>
<thead>
<tr>
<th>Parameter/command</th>
<th>SDG800</th>
<th>SDG1000</th>
<th>SDG2000X</th>
<th>SDG5000</th>
</tr>
</thead>
<tbody>
<tr>
<td>&lt;channel&gt;</td>
<td>no</td>
<td>yes</td>
<td>yes</td>
<td>yes</td>
</tr>
<tr>
<td>&lt;load&gt;( default unit is ohm)</td>
<td>50, HZ</td>
<td>50~10000, HZ</td>
<td>50~100000, HZ</td>
<td>50, HZ</td>
</tr>
</tbody>
</table>

1.6 Basic Wave Command

DESCRIPTION
Sets or gets basic wave parameters.

COMMAND SYNTAX
<channel>:BSWV(BaSic_WaVe) <parameter>
<channel>:= (C1, C2)
<parameter> := (a parameter from the table below)

<table>
<thead>
<tr>
<th>Parameters</th>
<th>Value</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>WVTP</td>
<td>&lt;type&gt;</td>
<td>Type of wave</td>
</tr>
<tr>
<td>FRQ</td>
<td>&lt;frequency&gt;</td>
<td>Value of frequency. If wave type is Noise or DC, you can't set this parameter.</td>
</tr>
<tr>
<td>PERI</td>
<td>&lt;period&gt;</td>
<td>Value of period. If wave type is Noise or DC, you can't set this parameter.</td>
</tr>
<tr>
<td>AMP</td>
<td>&lt;amplitude&gt;</td>
<td>Value of amplitude. If wave type is Noise or DC, you can't set this parameter.</td>
</tr>
<tr>
<td>OFST</td>
<td>&lt;offset&gt;</td>
<td>Value of offset. If wave type is Noise or DC, you can't set this parameter.</td>
</tr>
<tr>
<td>SYM</td>
<td>&lt;symmetry&gt;</td>
<td>Value of symmetry. Only when wave type is Ramp, you can set this parameter.</td>
</tr>
<tr>
<td>DUTY</td>
<td>&lt;duty&gt;</td>
<td>Value of duty cycle. Only when wave type is Square and Pulse, you can set this parameter.</td>
</tr>
<tr>
<td>PHSE</td>
<td>&lt;phase&gt;</td>
<td>Value of phase. If wave type is Noise or Pulse or DC, you can't set this parameter.</td>
</tr>
<tr>
<td>STDEV</td>
<td>&lt;stdev&gt;</td>
<td>Value of Noise wave stdev. Only when wave type is...</td>
</tr>
</tbody>
</table>
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<table>
<thead>
<tr>
<th>Parameter</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>MEAN</td>
<td>Value of Noise wave mean. Only when wave type is Noise, you can set this parameter.</td>
</tr>
<tr>
<td>WIDTH</td>
<td>Value of width. Only when wave type is Pulse, you can set this parameter.</td>
</tr>
<tr>
<td>RISE</td>
<td>Value of rise time. Only when wave type is Pulse, you can set this parameter.</td>
</tr>
<tr>
<td>FALL</td>
<td>Value of fall time. Only when wave type is Pulse, you can set this parameter.</td>
</tr>
<tr>
<td>DLY</td>
<td>Value of delay. Only when wave type is Pulse, you can set this parameter.</td>
</tr>
<tr>
<td>HLEV</td>
<td>Value of high level. If wave type is Noise or DC, you can’t set this parameter.</td>
</tr>
<tr>
<td>LLEV</td>
<td>Value of low level. If wave type is Noise or DC, you can’t set this parameter.</td>
</tr>
</tbody>
</table>

Note: if the command doesn’t set basic wave type, WVPT parameter will be set to current wave type.

where:

- `<type>`: `{SINE, SQUARE, RAMP, PULSE, NOISE, ARB, DC}`
- `<frequency>`: Default unit is "Hz". Value depends on the model.
- `<amplitude>`: Default unit is "V". Value depends on the model.
- `<offset>`: Default unit is "V". Value depends on the model.
- `<duty>`: 0% to 100%. Value depends on frequency.
- `<symmetry>`: 0% to 100%
- `<phase>`: Value depends on the model.
- `<stdev>`: Default unit is "V". Value depends on the model.
- `<mean>`: Default unit is "V". Value depends on the model.
- `<width>`: Max_width < (Max_duty * 0.01) * period and Min_width > (Min_duty * 0.01) * period.
- `<rise>`: Value depends on the model.
- `<fall>`: Value depends on the model.
- `<delay>`: Unit is S. Maximal is Pulse period, minimum value is 0.

### QUERY SYNTAX

- `<channel>`: BSWV (BaSic_ WaVe)?
- `<channel>`: `{C1, C2}`

### RESPONSE FORMAT

- `<channel>`: BSWV `<type>`, `<frequency>`, `<amplitude>`, `<offset>`, `<duty>`, `<symmetry>`, `<phase>`, `<variance>`, `<mean>`, `<width>`, `<rise>`, `<fall>`, `<delay>`.

### EXAMPLE

Change channel one wave type to ramp.

C1: BSWV WVTP, RAMP
Change frequency of channel one to 2000 Hz.
C1: BSWV FRQ, 2000

Set amplitude of channel one to 3Vpp.
C1: BSWV AMP, 3

Read channel basic wave parameters from device.
C1: BSWV?
Return:
C1: BSWV WVTP, SINE, FRQ, 100HZ, PERI, 0.01S, AMP, 2V, OFST, 0V, HLEV, 1V, LLEV, -1V, PHSE, 0

**RELATED COMMANDS**
ARWV, BTWV, MDWV, SWWV

**Note:**
Parameter/command SDG800 SDG1000 SDG2000X SDG5000

<table>
<thead>
<tr>
<th>Parameter/command</th>
<th>SDG800</th>
<th>SDG1000</th>
<th>SDG2000X</th>
<th>SDG5000</th>
</tr>
</thead>
<tbody>
<tr>
<td>&lt;channel&gt;</td>
<td>no (single channel)</td>
<td>yes</td>
<td>yes</td>
<td>yes</td>
</tr>
<tr>
<td>RISE</td>
<td>yes</td>
<td>no</td>
<td>yes</td>
<td>yes</td>
</tr>
<tr>
<td>FAL</td>
<td>yes</td>
<td>no</td>
<td>yes</td>
<td>yes</td>
</tr>
<tr>
<td>DLY</td>
<td>no</td>
<td>yes</td>
<td>yes</td>
<td>yes</td>
</tr>
</tbody>
</table>

**1.7 Modulate Wave Command**

**DESCRIPTION**
Sets or gets modulation parameters.

**COMMAND**

`<channel>:MDWV(MoDulateWaVe)<parameter>`

**SYNTAX**

`<channel>:= (C1, C2)`

`<parameter>:= {a parameter from the table below}`

**Parameters** | Value | Description
---|---|---
STATE | `<state>` | Turn on or off modulation. Note: if you want to set or read other parameters of modulation, you must set STATE to ON at first.
AM, SRC | `<src>` | AM signal source.
AM, MDSP | `<mod wave shape>` | AM modulation wave. Only when AM signal source is set to INT, you can set the parameter.
AM, FRQ | `<AM frequency>` | AM frequency. Only when AM signal source is set to INT, you can set the parameter.
AM, DEPTH | `<depth>` | AM depth. Only when AM signal source is set to INT, you can set the parameter.
<table>
<thead>
<tr>
<th>Signal Type</th>
<th>Source Type</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>DSBAM, SRC</td>
<td>&lt;src&gt;</td>
<td>DSBAM signal source.</td>
</tr>
<tr>
<td>DSBAM, MDSP</td>
<td>&lt;mod wave shape&gt;</td>
<td>DSBAM modulation wave. Only when AM signal source is set to INT, you can set the parameter.</td>
</tr>
<tr>
<td>DSBAM, FRQ</td>
<td>&lt;DSB-AM frequency&gt;</td>
<td>DSBAM frequency. Only when AM signal source is set to INT, you can set the parameter.</td>
</tr>
<tr>
<td>FM, SRC</td>
<td>&lt;src&gt;</td>
<td>FM signal source.</td>
</tr>
<tr>
<td>FM, MDSP</td>
<td>&lt;mod wave shape&gt;</td>
<td>FM modulation wave. Only when FM signal source is set to INT, you can set the parameter.</td>
</tr>
<tr>
<td>FM, FRQ</td>
<td>&lt;FM frequency&gt;</td>
<td>FM frequency. Only when FM signal source is set to INT, you can set the parameter.</td>
</tr>
<tr>
<td>FM, DEVI</td>
<td>&lt;FM frequency deviation&gt;</td>
<td>FM frequency deviation. Only when FM signal source is set to INT, you can set the parameter.</td>
</tr>
<tr>
<td>PM, SRC,</td>
<td>&lt;src&gt;</td>
<td>PM signal source.</td>
</tr>
<tr>
<td>PM, MDSP</td>
<td>&lt;mod wave shape&gt;</td>
<td>PM modulation wave. Only when PM signal source is set to INT, you can set the parameter.</td>
</tr>
<tr>
<td>PM, FRQ</td>
<td>&lt;PM frequency&gt;</td>
<td>PM frequency. Only when PM signal source is set to INT, you can set the parameter.</td>
</tr>
<tr>
<td>PWM, FRQ</td>
<td>&lt;PWM frequency&gt;</td>
<td>PWM frequency. Only when carrier wave is PULSE wave, you can set the parameter.</td>
</tr>
<tr>
<td>PWM, DEVI</td>
<td>&lt;PWM dev&gt;</td>
<td>Duty cycle deviation. Only when carrier wave is PULSE wave, you can set the parameter.</td>
</tr>
<tr>
<td>PWM, MDSP</td>
<td>&lt;mod wave shape&gt;</td>
<td>PWM modulation wave. Only when carrier wave is PULSE wave, you can set the parameter.</td>
</tr>
<tr>
<td>PWM, SRC</td>
<td>&lt;src&gt;</td>
<td>PWM signal source.</td>
</tr>
<tr>
<td>PM, DEVI</td>
<td>&lt;PM phase offset&gt;</td>
<td>PM phase deviation. Only when PM signal source is set to INT, you can set the parameter.</td>
</tr>
<tr>
<td>ASK, SRC</td>
<td>&lt;src&gt;</td>
<td>ASK signal source.</td>
</tr>
<tr>
<td>ASK, KFRQ</td>
<td>&lt;ASK key frequency&gt;</td>
<td>ASK key frequency. Only when ASK signal source is set to INT, you can set the parameter.</td>
</tr>
<tr>
<td>FSK, KFRQ</td>
<td>&lt;FSK frequency&gt;</td>
<td>FSK frequency. Only when FSK signal source is set to INT, you can set the parameter.</td>
</tr>
<tr>
<td>FSK, HFRQ</td>
<td>&lt;FSK hop frequency&gt;</td>
<td>FSK hop frequency.</td>
</tr>
<tr>
<td>FSK, SRC</td>
<td>&lt;src&gt;</td>
<td>FSK signal source.</td>
</tr>
</tbody>
</table>
CARR, WVT<wave type> Carrier wave type.
CARR, FRQ<frequency> Value of carrier frequency.
CARR, AMP<amplitude> Value of carrier amplitude.
CARR, OFST<offset> Value of carrier offset.
CARR, SYM<symmetry> Value of carrier symmetry. Only ramp can set this parameter.
CARR, DUTY<duty> Value of duty cycle. Only square and pulse can set this parameter.
CARR, PHSE<phase> Value of carrier phase.
CARR, RISE<rise> Value of rise time. Only Pulse can set this parameter.
CARR, FALL<fall> Value of fall time. Only Pulse can set this parameter.
CARR, DLY<delay> Value of carrier delay. Only PULSE can set this parameter.

Note: If carrier wave is Noise you can’t set to turn on modulation.
If you want to set AM, FM, PM, CARR and STATE the first parameter have to be one of them.

where:  
<state>= {ON, OFF}
<src>= {INT, EXT}
<mod wave shape>= {SINE, SQUARE, TRIANGLE, UP RAMP, DNRAMP, NOISE, ARB}
<am frequency>= {Default unit is "Hz". Value depends on the model.}
<depth>= {0% to 120%}
<fm frequency>= {Default unit is "Hz". Value depends on the model.}
<fm frequency deviation >= {0 to carrier frequency, Value depends on the difference between carrier frequency and bandwidth frequency.}
<pm frequency>= {Default unit is "Hz", Value depends on the model.}
<pm phase deviation >:= {0 to 360.}
<pwm frequency>= {Default unit is "Hz", Value depends on the model.}
<pwm dev>= {Default unit is ",value depends on carrier duty cycle}
<ask key frequency>= {Default unit is "Hz", Value depends on the model.}
<fsk frequency>= {Default unit is "Hz", Value depends on the version.}
<fsk jump frequency>= {the same with basic wave frequency}
<wave type>= {SINE, SQUARE, RAMP, ARB, PULSE}
<frequency> := {Default unit is "Hz", Value depends on the model.}
<amplitude>= {Default unit is "V", Value depends on the model.}
<offset>= {Default unit is "V", Value depends on the model.}
<duty>= {0% to 100%}
<symmetry>= {0% to 100%}
<phase>= {Value depends on the model.}
<rise>= {Value depends on the model.}
<fall>= {Value depends on the model.}
<delay>:= \{Default unit is "S".\}

Note:
There are some parameters Value depends on the model, You can read version datasheet to get specific parameters

**QUERY SYNTAX**

<channel>: MDWV (MoDulateWaVe)?
<channel>:=\{C1, C2\}

**RESPONSE FORMAT**

<channel>:MDWV <parameter>

<parameter> :=\{ Return all parameter of the current modulation parameters.\}

**EXAMPLE**

Set channel one modulation type to AM.
C1: MDWV AM

Set modulation shape to AM, and set AM modulating wave type to sine wave.
C1: MDWV AM, MDSP, SINE

Read channel one modulation parameters of which STATE is ON.
C1: MDWV?
Return:
C1:MDWV STATE,ON,AM,MDSP,SINE,SRC,INT,FRQ,100HZ, DEPTH,100,CARR,WVTP,RAMP,FRQ,1000HZ,AMP,4V,OFST,0V,PHSE, 0, SYM, 50

Read channel one modulate wave parameters of which STATE is OFF.
C1: MDWV?
Return:
C1: MDWV STATE, OFF

Set channel one FM frequency to 1000Hz
C1: MDWV FM, FRQ, 1000

Set channel one carrier shape to SINE.
C1: MDWV CARR, WVTP, SINE

Set channel one carrier frequency to 1000 Hz.
C1: MDWV CARR, FRQ,1000

**RELATED COMMANDS**

ARWV, BTWV, SWWV, BSWV
Remote Control Manual

Note:

<table>
<thead>
<tr>
<th>Parameter/command</th>
<th>SDG800</th>
<th>SDG1000</th>
<th>SDG2000X</th>
<th>SDG5000</th>
</tr>
</thead>
<tbody>
<tr>
<td>&lt;channel&gt;</td>
<td>No(s)</td>
<td>yes</td>
<td>yes</td>
<td>yes</td>
</tr>
<tr>
<td>[type], SRC</td>
<td>no(only internal source)</td>
<td>yes</td>
<td>yes</td>
<td>yes</td>
</tr>
<tr>
<td>CARR, DLY</td>
<td>no</td>
<td>yes</td>
<td>yes</td>
<td>yes</td>
</tr>
<tr>
<td>CARR, RISE</td>
<td>yes</td>
<td>no</td>
<td>yes</td>
<td>yes</td>
</tr>
<tr>
<td>CARR, FALL</td>
<td>yes</td>
<td>no</td>
<td>yes</td>
<td>yes</td>
</tr>
</tbody>
</table>

[type]:=(AM, FM, PM, FSK, ASK, DSBAM, PWM)

1.8 Sweep Wave Command

DESCRIPTION
Sets or gets sweep parameters.

COMMAND SYNTAX

- `<channel>`SWWV(SweepWaVe) `<parameter>`
- `<channel>`:={C1, C2}
- `<parameter>`:= (a parameter from the table below)

<table>
<thead>
<tr>
<th>Parameters</th>
<th>Value</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>STATE</td>
<td>&lt;state&gt;</td>
<td>Turn on or off sweep. Note: if you want to set or read other parameters you must set STATE to ON at first.</td>
</tr>
<tr>
<td>TIME</td>
<td>&lt;time&gt;</td>
<td>Value of sweep time.</td>
</tr>
<tr>
<td>STOP</td>
<td>&lt;stop frequency&gt;</td>
<td>Value of stop frequency.</td>
</tr>
<tr>
<td>START</td>
<td>&lt;start frequency&gt;</td>
<td>Value of start frequency.</td>
</tr>
<tr>
<td>TRSR</td>
<td>&lt;trigger src&gt;</td>
<td>Trigger source.</td>
</tr>
<tr>
<td>TRMD</td>
<td>&lt;trigger mode&gt;</td>
<td>State of trigger output. If TRSR is EXT, the parameter is invalid.</td>
</tr>
<tr>
<td>SWMD</td>
<td>&lt;sweep mode&gt;</td>
<td>Sweep style.</td>
</tr>
<tr>
<td>DIR</td>
<td>&lt;direction&gt;</td>
<td>Sweep direction.</td>
</tr>
<tr>
<td>EDGE</td>
<td>&lt;edge&gt;</td>
<td>Value of edge. Only when TRSR is EXT, the parameter is valid.</td>
</tr>
<tr>
<td>MTRIG</td>
<td>&lt;manual trigger&gt;</td>
<td>Make a manual trigger. Only when TRSR is MAN, the parameter is valid.</td>
</tr>
<tr>
<td>CARR, WVTP</td>
<td>&lt;wave type&gt;</td>
<td>Carrier type.</td>
</tr>
<tr>
<td>CARR, FRQ</td>
<td>&lt;frequency&gt;</td>
<td>Value of carrier frequency.</td>
</tr>
<tr>
<td>CARR, AMP</td>
<td>&lt;amplitude&gt;</td>
<td>Value of carrier amplitude.</td>
</tr>
<tr>
<td>CARR, OFST</td>
<td>&lt;offset&gt;</td>
<td>Value of carrier offset.</td>
</tr>
<tr>
<td>CARR, SYM</td>
<td>&lt;symmetry&gt;</td>
<td>Value of carrier symmetry, Only Ramp can set this parameter.</td>
</tr>
<tr>
<td>CARR,</td>
<td>&lt;duty&gt;</td>
<td>Value of carrier duty cycle. Only Square can set</td>
</tr>
</tbody>
</table>
DUTY | this parameter.
---|---
CARR, PHSE | <phase> Value of carrier phase.

Note: If carrier is Pulse or Noise you can’t turn on sweep. If you want to set CARR and STATE, the first parameter has to be one of them.

where:

- `<state>` := {ON, OFF}
- `<time>` := { Default unit is "S". Value depends on the model. }
- `<stop frequency>` := { the same with basic wave frequency }
- `<start frequency>` := { the same with basic wave frequency }
- `<trigger src>` := {EXT, INT, MAN}
- `<trigger mode>` := {ON, OFF}
- `<sweep mod>` := {LINE, LOG}
- `<direction>` := {UP, DOWN}
- `<edge>` := {RISE, FALL}
- `<wave type>` := {SINE, SQUARE, RAMP, ARB}
- `<frequency>` := { Default unit is "Hz". Value depends on the model. }
- `<amplitude>` := { Default unit is "V". Value depends on the model. }
- `<offset>` := { Default unit is "V", Value depends on the model. }
- `<duty>` := { 0% to 100 %.
- `<symmetry>` := { 0% to 100% }
- `<phase>` := { Value depends on the model. }

Note:
There are some parameters Value depends on the model, You can read version datasheet.

**QUERY SYNTAX**

- `<channel>`: SWWV (SWeepWaVe)? `<channel>`:= {C1, C2}

**RESPONSE FORMAT**

- `<parameter>` := { Return all parameters of the current sweep wave. }

**EXAMPLE**

Set channel one sweep time to 1 S.
C1: SWWV TIME, 1

Set channel one sweep stop frequency to 1000 Hz.
C1: SWWV STOP, 1000

Read channel one sweep parameters of which STATE is ON.
C2: SWWV?
Return:
C2: SWWV STATE, ON, TIME, 1S, STOP, 100HZ, START, 100HZ, TRSR, MAN, TRMD, OFF, SWMD, LINE, DIR, UP, CARR, WVTP, SQUARE, FRQ, 1000HZ, AMP, 4V, OFST, 0V, DUTY, 50, PHSE, 0

Read channel two sweep parameters of which STATE is OFF.
C2: SWWV?
Return:
C2: SWWV STATE, OFF

Notes:

<table>
<thead>
<tr>
<th>Parameter/command</th>
<th>SDG800</th>
<th>SDG1000</th>
<th>SDG2000X</th>
<th>SDG5000</th>
</tr>
</thead>
<tbody>
<tr>
<td>&lt;channel&gt;</td>
<td>no(singl channel)</td>
<td>yes</td>
<td>yes</td>
<td>yes</td>
</tr>
<tr>
<td>TRMD</td>
<td>no</td>
<td>yes</td>
<td>yes</td>
<td>yes</td>
</tr>
<tr>
<td>EDGE</td>
<td>no</td>
<td>yes</td>
<td>yes</td>
<td>yes</td>
</tr>
</tbody>
</table>

1.9 Burst Wave Command

DESCRIPTION
Sets or gets burst wave parameters.

COMMAND SYNTAX
<channel>BTWV(BursTWaVe) <parameter>
<channel>::=(C1, C2)
<parameter>::=(a parameter from the table below)

<table>
<thead>
<tr>
<th>Parameters</th>
<th>Value</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>STATE</td>
<td>&lt;state&gt;</td>
<td>Turn on or off burst. Note: If you want to set or read other parameters of burst, you must set state to ON at first.</td>
</tr>
<tr>
<td>PRD</td>
<td>&lt;period&gt;</td>
<td>Value of burst period. When carrier is NOISE wave, you can’t set it. When GATE was chosen, you can’t set it (but in SDG2000X, you can). And when trigger source is EXT, you can’t set it.</td>
</tr>
<tr>
<td>STPS</td>
<td>&lt;start phase&gt;</td>
<td>Start phase of carrier. When carrier is NOISE or PULSE wave, you can’t set it.</td>
</tr>
<tr>
<td>GATE_NCYC</td>
<td>&lt;gate Ncycle&gt;</td>
<td>Set the burst mode to GATE or NCYC. When carrier is NOISE, you can’t set it.</td>
</tr>
<tr>
<td>TRSR</td>
<td>&lt;trigger source&gt;</td>
<td>Set the trigger source.</td>
</tr>
<tr>
<td>DLAY</td>
<td>&lt;delay&gt;</td>
<td>Value of delay. When carrier is NOISE wave, you can’t set it. When NCYC is chosen you can set it.</td>
</tr>
<tr>
<td>PLRT</td>
<td>&lt;polarity&gt;</td>
<td>Value of polarity. When GATE is chosen you can set it. When carrier is NOISE, it is the only parameter.</td>
</tr>
<tr>
<td>Code</td>
<td>Description</td>
<td>Value Information</td>
</tr>
<tr>
<td>-------</td>
<td>--------------------------------------</td>
<td>-----------------------------------------------------------------------------------</td>
</tr>
<tr>
<td>TRMD</td>
<td>&lt;trig mode&gt;</td>
<td>Value of trigger mode. When carrier is NOISE wave, you can’t set it. When NCYC is chosen you can set it. When TRSR is set to EXT, you can’t set it.</td>
</tr>
<tr>
<td>EDGE</td>
<td>&lt;edge&gt;</td>
<td>Value of edge. When carrier is NOISE wave, you can’t set it. When NCYC is chosen you can set it. When TRSR is set to EXT, you can’t set it.</td>
</tr>
<tr>
<td>TIME</td>
<td>&lt;circle time&gt;</td>
<td>Value of Ncycle number. When carrier is NOISE wave, you can’t set it. When NCYC is chosen you can set it.</td>
</tr>
<tr>
<td>MTRIG</td>
<td>&lt;manual trig&gt;</td>
<td>Manual trigger. When TRSR is set to MAN, it can be set.</td>
</tr>
<tr>
<td>CARR, WVTP</td>
<td>&lt;wave type&gt;</td>
<td>Value of carrier type.</td>
</tr>
<tr>
<td>CARR, FRQ</td>
<td>&lt;frequency&gt;</td>
<td>Value of carrier frequency</td>
</tr>
<tr>
<td>CARR, AMP</td>
<td>&lt;amplitude&gt;</td>
<td>Value of carrier amplitude.</td>
</tr>
<tr>
<td>CARR, OFST</td>
<td>&lt;offset&gt;</td>
<td>Value of carrier offset.</td>
</tr>
<tr>
<td>CARR, SYM</td>
<td>&lt;symmetry&gt;</td>
<td>Value of symmetry. Only Ramp can set this parameter.</td>
</tr>
<tr>
<td>CARR, DUTY</td>
<td>&lt;duty&gt;</td>
<td>Value of duty cycle. Only Square or Pulse can set this parameter.</td>
</tr>
<tr>
<td>CARR, PHSE</td>
<td>&lt;phase&gt;</td>
<td>Value of carrier phase.</td>
</tr>
<tr>
<td>CARR, RISE</td>
<td>&lt;rise&gt;</td>
<td>Value of rise edge. Only when carrier is Pulse, the Value is valid.</td>
</tr>
<tr>
<td>CARR, FALL</td>
<td>&lt;fall&gt;</td>
<td>Value of fall edge. Only when carrier is Pulse, the Value is valid.</td>
</tr>
<tr>
<td>CARR, STDEV</td>
<td>&lt;stdev&gt;</td>
<td>Value of stdev. Only when carrier is Noise, the Value is valid.</td>
</tr>
<tr>
<td>CARR, MEAN</td>
<td>&lt;mean&gt;</td>
<td>Value of mean. Only when carrier wave is Noise, the Value is valid.</td>
</tr>
<tr>
<td>CARR, DLY</td>
<td>&lt;delay&gt;</td>
<td>Value of delay. Only when carrier is Pulse, the parameter is valid</td>
</tr>
</tbody>
</table>

Note: If you want to set CARR and STATE, the first parameter has to one of them

where:  
<state>:= {ON, OFF}  
<period>:= {Default unit is "S", Value depends on the model.}  
<start phase>:= {0 to 360}  
<gate ncycle>:= {GATE, NCYC}  
<trigger source>:= {EXT, INT, MAN}  
<delay>:= {Default unit is "S", Value depends on the model.}  
<polarity>:= {NEG, POS}  
<trig mode >:= {RISE, FALL, OFF}
<edge> := {RISE, FALL}
<circle time> := {Value depends on the Model ("INF" means infinite).}
<wave type> := {SINE, SQUARE, RAMP, PULSE, NOISE, ARB}
<frequency> := {Default unit is "HZ". Value depends on the model.}
<amplitude> := {Default unit is "V". Value depends on the model.}
<offset> := {Default unit is "V". Value depends on the model.}
<duty> := {0% to 100%}
<symmetry> := {0% to 100%}
<phase> := {Value depends on the model.}
<stdev> := {Default unit is "V". Value depends on the model.}
<mean> := {Default unit is "V". Value depends on the model.}
<width> := {Max_width < (Max_duty * 0.01) * period and Min_width > (Min_duty * 0.01) * period.}
<rise> := {Value depends on the model.}
<fall> := {Value depends on the model.}
<delay> := {Default unit is “S”}

Note:
There are some parameters Value depends on the model,
You can read version datasheet to get specific parameters.

QUERY SYNTAX
<channel>: BTWV (BurstTWaVe)? <parameter>
<channel> := {C1, C2}
<parameter> := <period>……

RESPONSE FORMAT
<channel>: BTWV <type>, <state>, <period>……

EXAMPLE
Set channel one burst period to 1S.
C1: BTWV PRD, 1

Set channel one burst delay to 1s
C1: BTWV DLAY, 1

Set channel one burst to infinite
C1: BTWV TIME, INF

Read channel two burst parameters of which STATE is ON.
C2: BTWV?
Return:
C2: BTWV STATE, ON, PRD, 0.01S, STPS, 0, TRSR, INT, TRMD, OFF, TIME, 1, DLAY, 2.4e-07S, GATE_NCYC, NCYC,
CARR, WVTP, SINE, FRQ, 1000HZ, AMP, 4V, OFST, 0V, PHSE, 0

Read channel two burst parameters of which STATE is OFF.
C2: BTWV?
Return:
C2: BTWV STATE, OFF

Notes:

<table>
<thead>
<tr>
<th>Parameter/command</th>
<th>SDG800</th>
<th>SDG1000</th>
<th>SDG2000X</th>
<th>SDG5000</th>
</tr>
</thead>
<tbody>
<tr>
<td>&lt;channel&gt;</td>
<td>no (single</td>
<td>yes</td>
<td>yes</td>
<td>yes</td>
</tr>
<tr>
<td>TRMD</td>
<td>no</td>
<td>yes</td>
<td>yes</td>
<td>yes</td>
</tr>
<tr>
<td>EDGE</td>
<td>no</td>
<td>yes</td>
<td>yes</td>
<td>yes</td>
</tr>
<tr>
<td>CARR, DLY</td>
<td>yes</td>
<td>yes</td>
<td>yes</td>
<td>yes</td>
</tr>
<tr>
<td>CARR, RISE</td>
<td>yes</td>
<td>no</td>
<td>yes</td>
<td>yes</td>
</tr>
<tr>
<td>CARR, FALL</td>
<td>yes</td>
<td>no</td>
<td>yes</td>
<td>yes</td>
</tr>
</tbody>
</table>

### 1.10 Parameter Copy Command

**DESCRIPTION**
Copies parameters from one channel to the other.

**COMMAND SYNTAX**
PACP(ParaCoPy) <destination channel>, <src channel>
<destination channel> := \{C1, C2\}
<src channel> := \{C1, C2\}
Note: the parameters C1 and C2 must be set to the device together.

**EXAMPLE**
Copy parameters from channel one to channel two.
PACP C2, C1

**RELATED COMMANDS**
ARWV, BTWV, MDWV, SWWV, BSWV

**Note:**

<table>
<thead>
<tr>
<th>Parameter/command</th>
<th>SDG800</th>
<th>SDG1000</th>
<th>SDG2000X</th>
<th>SDG5000</th>
</tr>
</thead>
<tbody>
<tr>
<td>PACP</td>
<td>no</td>
<td>yes</td>
<td>yes</td>
<td>yes</td>
</tr>
</tbody>
</table>

### 1.11 Arbitrary Wave Command

**DESCRIPTION**
Sets and gets arbitrary wave type.
COMMAND SYNTAX

<channel> ARWV(ArbWaVe) INDEX,<value1>, NAME,<value2>
<channel>:=C1, C2
< value1>: the table below shows what the index number mean.)
< value2>: see table below.

QUERY SYNTAX

<channel>: ARWV (ARbWaVe)?
<channel>:=C1, C2

RESPONSE FORMAT

<channel>:ARWV <index>

EXAMPLE

Set StairUp arbitrary wave output by index.
C1:ARWV INDEX, 2

Read system current wave.
ARWV?
Return:
ARWV INDEX,2,NAME,StairUp

Set Cardiac arbitrary wave output by name.
ARWV NAME, Cardiac

RELATED COMMANDS

BSWV

<table>
<thead>
<tr>
<th>Index</th>
<th>Name</th>
<th>Index</th>
<th>Name</th>
<th>Index</th>
<th>Name</th>
<th>Index</th>
<th>Name</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>StairUp</td>
<td>12</td>
<td>Sqrt</td>
<td>24</td>
<td>Cardiac</td>
<td>36</td>
<td>Bartlett</td>
</tr>
<tr>
<td>1</td>
<td>StairDn</td>
<td>13</td>
<td>Root3</td>
<td>25</td>
<td>Quake</td>
<td>37</td>
<td>Tan</td>
</tr>
<tr>
<td>2</td>
<td>Stairud</td>
<td>14</td>
<td>X^2</td>
<td>26</td>
<td>Chirp</td>
<td>38</td>
<td>Cot</td>
</tr>
<tr>
<td>3</td>
<td>Ppulse</td>
<td>15</td>
<td>X^3</td>
<td>27</td>
<td>Twotone</td>
<td>39</td>
<td>Sec</td>
</tr>
<tr>
<td>4</td>
<td>Npulse</td>
<td>16</td>
<td>Sinc</td>
<td>28</td>
<td>Snr</td>
<td>40</td>
<td>Csc</td>
</tr>
<tr>
<td>5</td>
<td>Trapezia</td>
<td>17</td>
<td>Gaussian</td>
<td>29</td>
<td>Hamming</td>
<td>41</td>
<td>Asin</td>
</tr>
<tr>
<td>6</td>
<td>Upramp</td>
<td>18</td>
<td>Dlorentz</td>
<td>30</td>
<td>Hanning</td>
<td>42</td>
<td>Acos</td>
</tr>
<tr>
<td>7</td>
<td>Dnramp</td>
<td>19</td>
<td>Haversine</td>
<td>31</td>
<td>Kaiser</td>
<td>43</td>
<td>Atan</td>
</tr>
<tr>
<td>8</td>
<td>Exp_fall</td>
<td>20</td>
<td>Lorentz</td>
<td>32</td>
<td>Blackman</td>
<td>44</td>
<td>Acot</td>
</tr>
<tr>
<td>9</td>
<td>Exp_rise</td>
<td>21</td>
<td>Gauspuls</td>
<td>33</td>
<td>Gausswin</td>
<td></td>
<td></td>
</tr>
<tr>
<td>10</td>
<td>Logfall</td>
<td>22</td>
<td>Gmonopuls</td>
<td>34</td>
<td>Triang</td>
<td></td>
<td></td>
</tr>
<tr>
<td>11</td>
<td>Logrise</td>
<td>23</td>
<td>Tripuls</td>
<td>35</td>
<td>Harris</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

About the table: This table is just an example, the index may depend on the model. You can execute “STL?” command to get them accurately.

Notes:

<table>
<thead>
<tr>
<th>Parameter/command</th>
<th>SDG800</th>
<th>SDG1000</th>
<th>SDG2000X</th>
<th>SDG5000</th>
</tr>
</thead>
<tbody>
<tr>
<td>&lt;channel&gt;</td>
<td>no(singl e channel)</td>
<td>yes</td>
<td>yes</td>
<td>yes</td>
</tr>
</tbody>
</table>
1.12 Sync Command

DESCRIPTION
Sets synchronization signal.

COMMAND SYNTAX
<channel>: SYNC <parameter>
<channel>:= (C1, C2)
<parameter>:= {ON, OFF}

QUERY SYNTAX
<channel>: SYNC?
<channel>:= (C1, C2)

RESPONSE FORMAT
<channel>: SYNC <parameter>

EXAMPLE
Turn on sync function of channel one.
C1: SYNC ON

Read state of channel one sync.
C1: SYNC?
Return:
C1: SYNC OFF

Note:
<table>
<thead>
<tr>
<th>Parameter/command</th>
<th>SDG800</th>
<th>SDG1000</th>
<th>SDG2000X</th>
<th>SDG5000</th>
</tr>
</thead>
<tbody>
<tr>
<td>SYNC</td>
<td>no</td>
<td>yes</td>
<td>yes</td>
<td>yes</td>
</tr>
</tbody>
</table>

1.13 Number Format Command

DESCRIPTION
Sets or gets number format.

COMMAND SYNTAX
NBFM(Number_Format) <parameter>
<parameter> := (a parameter from the table below.)

<table>
<thead>
<tr>
<th>Parameters</th>
<th>Value</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>PNT</td>
<td>&lt;pnt&gt;</td>
<td>Point format</td>
</tr>
<tr>
<td>SEPT</td>
<td>&lt;sept&gt;</td>
<td>Separator format</td>
</tr>
</tbody>
</table>

Where:
<pnt> := {Dot, Comma}.
<sept> := {Space, Off, On}.

QUERY SYNTAX
NBFM(Number_Format)?
1.14 Language Command

DESCRIPTION
Sets or gets system language.

COMMAND SYNTAX
LAGG(LAnGuaGe) <parameter>
<parameter>:={EN, CH, RU}

QUERY SYNTAX
LAGG (LAnGuaGe)?

RESPONSE FORMAT
LAGG <parameter>

EXAMPLE
Set language to English.
LAGG EN
Read language
LAGG?
Return:
LAGG EN

Note:

<table>
<thead>
<tr>
<th>Parameter/command</th>
<th>SDG800</th>
<th>SDG1000</th>
<th>SDG2000X</th>
<th>SDG5000</th>
</tr>
</thead>
<tbody>
<tr>
<td>RU</td>
<td>no</td>
<td>yes</td>
<td>no</td>
<td>no</td>
</tr>
</tbody>
</table>

1.15 Configuration Command

DESCRIPTION
Sets or gets the power-on system setting.
COMMAND SYNTAX  SCFG(Sys_CFG)<parameter>
<parameter>:= (DEFAULT, LAST)

QUERY SYNTAX  SCFG (Sys_CFG)?

RESPONSE FORMAT  SCFG <parameter>

EXAMPLE  Set the power-on system setting to LAST.
          SCFG LAST

1.16  Buzzer Command

DESCRIPTION  Turns on or off the buzzer.

COMMAND SYNTAX  BUZZ(BUZZer) <parameter>
<parameter>:= (ON, OFF)

QUERY SYNTAX  BUZZ (BUZZer)?

RESPONSE FORMAT  BUZZ <parameter>

EXAMPLE  Turn on the buzzer.
          BUZZ ON

1.17  Screen Save Command

DESCRIPTION  Turns off or sets screen save time (default unit is minutes).

COMMAND SYNTAX  SCSV (SCreen_SaVe) <parameter>
<parameter>:= (OFF, 1, 5, 15, 30, 60, 120, 300)

QUERY SYNTAX  SCSV (SCreen_SaVe)?

RESPONSE FORMAT  SCreen_SaVe <parameter>

EXAMPLE  Set screen save time to 5 minutes.
          SCSV 5

          Read the current screen save time.
          SCreen_SaVe?
1.18 Clock Source Command

DESCRIPTION
Sets or gets the clock source.

COMMAND SYNTAX
ROSC (ROSCillator) <parameter>
<parameter>:= {INT, EXT}

QUERY SYNTAX
ROSC (ROSCillator)?

RESPONSE FORMAT
ROSC <parameter>

EXAMPLE
Set internal time base as the clock source.
ROSC INT

Note:

<table>
<thead>
<tr>
<th>Parameter/command</th>
<th>SDG800</th>
<th>SDG1000</th>
<th>SDG2000X</th>
<th>SDG5000</th>
</tr>
</thead>
<tbody>
<tr>
<td>ROSC</td>
<td>no</td>
<td>yes</td>
<td>yes</td>
<td>yes</td>
</tr>
</tbody>
</table>

1.19 Frequency Counter Command

DESCRIPTION
Sets or gets frequency counter parameters.

COMMAND SYNTAX
FCNT(FreqCounter) <parameter>
<parameter>:= {a parameter from the table below}

<table>
<thead>
<tr>
<th>Parameters</th>
<th>Value</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>STATE</td>
<td>&lt;state&gt;</td>
<td>State of frequency counter.</td>
</tr>
<tr>
<td>FRQ</td>
<td>&lt;frequency&gt;</td>
<td>Value of frequency. Can’t be set.</td>
</tr>
<tr>
<td>PW</td>
<td>&lt;position width&gt;</td>
<td>Value of positive width. Can’t be set.</td>
</tr>
<tr>
<td>NW</td>
<td>&lt;negative width&gt;</td>
<td>Value of negative width. Can’t be set.</td>
</tr>
<tr>
<td>DUTY</td>
<td>&lt;duty&gt;</td>
<td>Value of duty cycle. Can’t be set.</td>
</tr>
<tr>
<td>FRQDEV</td>
<td>&lt;freq deviation&gt;</td>
<td>Value of freq deviation. Can’t be set.</td>
</tr>
<tr>
<td>REFQ</td>
<td>&lt;ref freq&gt;</td>
<td>Value of reference freq.</td>
</tr>
<tr>
<td>TRG</td>
<td>&lt;triglev&gt;</td>
<td>Value of trigger level.</td>
</tr>
<tr>
<td>MODE</td>
<td>&lt;mode&gt;</td>
<td>Value of mode.</td>
</tr>
<tr>
<td>HFR</td>
<td>&lt;HFR&gt;</td>
<td>State of HFR.</td>
</tr>
</tbody>
</table>

where:
<state>:= {ON, OFF}

<frequency>:= {Default unit is "Hz". Value range depends on the model.}
QUERY SYNTAX
FCNT (FreqCounter)?

RESPONSE FORMAT
FCNT < state ><frequency><duty>
<ref freq><triglev><position width><negative width>
<freq deviation><mode><HFR>

EXAMPLE

Turn on frequency counter:
FCNT STATE,ON

Query frequency counter information:
FCNT?
Return:
FCNT
STATE,ON,FRQ,0HZ,DUTY,0,REFQ,1e+07HZ,TRG,0V,PW,0
S,NW,0S,FRQDEV,-1e+06ppm,MODE,AC,HFR,OFF

Note:

<table>
<thead>
<tr>
<th>Parameter/command</th>
<th>SDG800</th>
<th>SDG1000</th>
<th>SDG2000X</th>
<th>SDG5000</th>
</tr>
</thead>
<tbody>
<tr>
<td>FCNT</td>
<td>no</td>
<td>yes</td>
<td>yes</td>
<td>yes</td>
</tr>
</tbody>
</table>

1.20 Invert Command

DESCRIPTION
Sets or gets polarity of current channel.

COMMAND SYNTAX
<channel>:INVT(INVerT) <parameter>
<channel>:= {C1, C2}
<parameter>:= {ON, OFF}

QUERY SYNTAX
<channel>: INVT (INVerT)?
<channel>:= {C1, C2}

RESPONSE FORMAT
<channel>:INVerT <parameter>

EXAMPLE

Set C1 ON:
C1: INVT ON

Read the polarity of channel one.
C1: INVT?
Return:
C1: INVT ON

Note:
1. Parameter/command list

<table>
<thead>
<tr>
<th>Parameter/command</th>
<th>SDG800</th>
<th>SDG1000</th>
<th>SDG2000X</th>
<th>SDG5000</th>
</tr>
</thead>
<tbody>
<tr>
<td>&lt;channel&gt;</td>
<td>no(singl</td>
<td>e channel)</td>
<td>yes</td>
<td>yes</td>
</tr>
</tbody>
</table>

2. The <channel> is a selectable parameter. If channel is not set, default is current channel.

1.21 Coupling Command

**DESCRIPTION**
Sets or gets channel coupling parameters.

**COMMAND SYNTAX**
COUP (COUPling)<parameter>

<parameter> := {a parameter from the table below}

<table>
<thead>
<tr>
<th>Parameters</th>
<th>Value</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>STATE</td>
<td>&lt;state&gt;</td>
<td>State of channel coupling.</td>
</tr>
<tr>
<td>BSCH</td>
<td>&lt;bsch&gt;</td>
<td>Value of bsch.</td>
</tr>
<tr>
<td>FDEV</td>
<td>&lt;frq_dev&gt;</td>
<td>Value of frq_dev.</td>
</tr>
<tr>
<td>PDEV</td>
<td>&lt;pha_dev&gt;</td>
<td>Value of position pha_dev.</td>
</tr>
</tbody>
</table>

where:
- <state> := {ON, OFF}
- <bsch> := {CH1, CH2}
- <frq_dev> := {Default unit is “Hz”}
- <pha_dev> := {Default unit is “°”}

**QUERY SYNTAX**
COUP (COUPling)?

**RESPONSE FORMAT**
COUP < state>,< bsch>,< frq_dev >,< pha_dev >

Note:

<table>
<thead>
<tr>
<th>Parameter/command</th>
<th>SDG800</th>
<th>SDG1000</th>
<th>SDG2000X</th>
<th>SDG5000</th>
</tr>
</thead>
<tbody>
<tr>
<td>Coupling</td>
<td>no</td>
<td>yes</td>
<td>no</td>
<td>no</td>
</tr>
</tbody>
</table>

1.22 Voltage Overload Command

**DESCRIPTION**
Sets or gets state of over-voltage protection.

**COMMAND SYNTAX**
VOLTPRT<parameter>
<parameter> ::= \{ ON, OFF \}

**QUERY SYNTAX**

VOLTPRT?

**RESPONSE FORMAT**

VOLTPRT<parameter>

<table>
<thead>
<tr>
<th>Parameter/command</th>
<th>SDG800</th>
<th>SDG1000</th>
<th>SDG2000X</th>
<th>SDG5000</th>
</tr>
</thead>
<tbody>
<tr>
<td>VOLTPRT/ command</td>
<td>no</td>
<td>yes</td>
<td>yes</td>
<td>no</td>
</tr>
</tbody>
</table>

### 1.23 Store list command

**DESCRIPTION**

This command is used to read the stored wave data names. If the store unit is empty, the command will return “EMPTY” string.

Note: M50~ M59 is user defined memory. The name will return what you defined. If you do not define an arbitrary name, it will return “EMPTY” (It depends on the model).

**QUERY SYNTAX**

STL (StoreList)? BUILDIN, USER

**EXAMPLE**

Read all arbitrary data saved in the device.

STL?

Return:

STL M0, StairUp, M1, StairDn, M2, StairUD, M3, Trapezia, M4, ExpFall, M5, ExpRise, M6, LogFall, M7, LogRise, M8, Sqr, M9, X^2, M10, Sinc, M11, Gaussian, M12, Dlorentz, M13, Haversine, M14, Lorentz, M15, Gauspuls, M16, Gmonopuls, M17, Cardiac, M18, Quake, M19, TwoTone, M20, SNR, M21, Hamming, M22, Hanning, M23, Kaiser, M24, Blackman, M25, GaussWin, M26, Harris, M27, Bartlett, M28, Tan, M29, Cot, M30, Sec, M31, Csc, M32, Asin, M33, Acos, M34, Atan, M35, ACot, M36, EMPTY, M37 ......

Read built-in wave data.

STL? BUILDIN

Return:

STL M0, Sine, M1, Noise, M10, ExpFal, M11, ExpRise, M12, LogFall, M13, LogRise, M14, Sqr, M15, Root3, M16, X^2, M17, X^3, M18, Sinc, M19, Gaussian, M2, StairUp, M20, Dlorentz, M21, Haversine, M22, Lorentz, M23, Gauspuls, M24, Gmonopuls, M25, Tripuls, M26, Cardiac, M27, Quake,
M28, Chirp, M29, Twotone, M3, StairDn, M30, SNR, M31, Hamming, M32, Hanning, M33, kaiser, M34, Blackman, M35, Gausswin, M36, Triang, M37, Harris, M38, Bartlett, M39, Tan, M4, StairUD, M40, Cot, M41, Sec, M42, Csc, M43, Asin, M44, Acos, M45, Atan, M46, Acot, M47, Square, M5, Ppulse, M6, Npulse, M7, Trapezia, M8, Upramp, M9, Dnramp

Read wave data defined by user.
STL? USER
Return:
STL
WVNM,sinec_8M,sinec_3000000,sinec_1664000,ramp_8M,sinec_2000000,sinec_500000,square_8M,sinec_5000,wave1,square_1M

Notes:
<table>
<thead>
<tr>
<th>Parameter/command</th>
<th>SDG800</th>
<th>SDG1000</th>
<th>SDG2000X</th>
<th>SDG5000</th>
</tr>
</thead>
<tbody>
<tr>
<td>BUILDIN</td>
<td>no</td>
<td>no</td>
<td>yes</td>
<td>no</td>
</tr>
<tr>
<td>USER</td>
<td>No</td>
<td>no</td>
<td>yes</td>
<td>no</td>
</tr>
</tbody>
</table>

1.24 Virtual key command

DESCRIPTION
The Command is used to send a simulate operation of pressing key on front panel.

COMMAND SYNTAX
VKEY (VirtualKEY) VALUE,<value>,STATE,<state>
<value> := (a parameter from the table below.)
<state> :=<0,1>( “1” is effective to virtual value, and “0” is useless )

EXAMPLE
VKEY VALUE,15, STATE,1
VKEY VALUE,KB_SWEEP, STATE,1

Note:
<table>
<table>
<thead>
<tr>
<th>KB_FUNC1</th>
<th>KB_FUNC2</th>
<th>KB_FUNC3</th>
<th>KB_FUNC4</th>
<th>KB_FUNC5</th>
<th>KB_FUNC6</th>
<th>KB_MOD</th>
<th>KB_SWEEP</th>
</tr>
</thead>
<tbody>
<tr>
<td>28</td>
<td>23</td>
<td>18</td>
<td>13</td>
<td>8</td>
<td>3</td>
<td>15</td>
<td>16</td>
</tr>
<tr>
<td>KB_NUMBER_4</td>
<td>KB_NUMBER_5</td>
<td>KB_NUMBER_6</td>
<td>KB_NUMBER_7</td>
<td>KB_NUMBER_8</td>
<td>KB_NUMBER_9</td>
<td>KB_POINT</td>
<td>KB_NEGATIVE</td>
</tr>
<tr>
<td>52</td>
<td>53</td>
<td>54</td>
<td>55</td>
<td>56</td>
<td>57</td>
<td>46</td>
<td>43</td>
</tr>
</tbody>
</table>
### 1.25 IP Command

**DESCRIPTION**  
The Command can set and get system IP address.

**COMMAND SYNTAX**  
SYST:COMM:LAN:IPAD  
(SYS TEM:COMMunicate:LAN:IPADdress)  
<parameter1>.<parameter2>.<parameter3>.<parameter4>

- <parameter1>:= {a integer value between 1 and 223}
- <parameter2>:= {a integer value between 0 and 255}
- <parameter3>:= {a integer value between 0 and 255}
- <parameter4>:= {a integer value between 0 and 255}

**QUERY SYNTAX**  
SYST:COMM:LAN:IPAD  
(SYS TEM:COMMunicate:LAN:IPADdress)?

**EXAMPLES**  
Set IP address to 10.11.13.203  
SYSTem: COMMunicate: LAN:IPADdress 10.11.13.203

Get IP address.  
SYST:COMM:LAN:IPAD?  
Return:  
"10.11.13.203"

**Note:**

<table>
<thead>
<tr>
<th>Parameter/command</th>
<th>SDG800</th>
<th>SDG1000</th>
<th>SDG2000X</th>
<th>SDG5000</th>
</tr>
</thead>
<tbody>
<tr>
<td>SYST:COMM:LAN:IPAD</td>
<td>no</td>
<td>no</td>
<td>yes</td>
<td>no</td>
</tr>
</tbody>
</table>
1.26 Subnet Mask Command

DESCRIPTION
The Command can set and get system subnet mask.

COMMAND SYNTAX
<parameter1>.<parameter2>.<parameter3>.<parameter4>

<parameter1>:= {a integer value between 0 and 255}
<parameter2>:= {a integer value between 0 and 255}
<parameter3>:= {a integer value between 0 and 255}
<parameter4>:= {a integer value between 0 and 255}

QUERY SYNTAX
SYSTem:COMMunicate:LAN:SMASk

EXAMPLES
Set subnet mask to 255.0.0.0
SYSTem:COMMunicate:LAN:SMASk 255.0.0.0

Get subnet mask
SYSTem:COMMunicate:LAN:SMASk?
Return:
“255.0.0.0”

<table>
<thead>
<tr>
<th>Parameter/command</th>
<th>SDG800</th>
<th>SDG1000</th>
<th>SDG2000X</th>
<th>SDG5000</th>
</tr>
</thead>
<tbody>
<tr>
<td>SYST:COMM:LAN:SMAS</td>
<td>no</td>
<td>no</td>
<td>yes</td>
<td>no</td>
</tr>
</tbody>
</table>

1.27 Gateway Command

DESCRIPTION
The Command can set and get system Gateway.

COMMAND SYNTAX
<parameter1>.<parameter2>.<parameter3>.<parameter4>

<parameter1>:= {a integer value between 0 and 223}
<parameter2>:= {a integer value between 0 and 255}
<parameter3>:= {a integer value between 0 and 255}
<parameter4>:= {a integer value between 0 and 255}

QUERY SYNTAX
SYSTem:COMMunicate:LAN:GAateway?
EXAMPLES

Set Gateway to 10.11.13.5:
SYSTem:COMMunicate:LAN:GATEway 10.11.13.5

Get gateway:
SYSTem:COMMunicate:LAN:GATEway?
Return:
"10.11.13.5"

<table>
<thead>
<tr>
<th>Parameter/command</th>
<th>SDG800</th>
<th>SDG1000</th>
<th>SDG2000X</th>
<th>SDG5000</th>
</tr>
</thead>
<tbody>
<tr>
<td>SYST:COMM:LAN:GAT</td>
<td>no</td>
<td>no</td>
<td>yes</td>
<td>no</td>
</tr>
</tbody>
</table>

1.28 Sampling Rate Command

DESCRIPTION
Sets or gets arb mode and sampling rate.
Note:
You can set or get sampling rate only in TrueArb mode.

COMMAND SYNTAX

<channel>:SRATE(SampleRATE) MODE <parameter1>, VALUE, <parameter2>
<channel> :=<C1, C2>
<parameter1> :=< DDS, TARB>
<parameter2> :={ a integer value between 1e-6 and 75000000, (default unit is Sa/s)}

QUERY SYNTAX

<channel>: SRATE?

EXAMPLES

Get the channel one sample rate value
C1: SRATE?
Return:
C1: SRATE MODE, DDS
Set channel one to TrueArb mode.
C1: SRATE MODE, TARB

Set channel one sample rate value to 10000000Sa/s.
C1: SRATE VALUE, 1000000

<table>
<thead>
<tr>
<th>Parameter/command</th>
<th>SDG800</th>
<th>SDG1000</th>
<th>SDG2000X</th>
<th>SDG5000</th>
</tr>
</thead>
<tbody>
<tr>
<td>&lt;channel&gt;</td>
<td>No(singl channel)</td>
<td>yes</td>
<td>yes</td>
<td>yes</td>
</tr>
<tr>
<td>SRATE</td>
<td>no</td>
<td>no</td>
<td>yes</td>
<td>no</td>
</tr>
</tbody>
</table>
1.29 Index

*IDN
OPC
*CLS
*ESE
*ESR
*RST
*SRE
*STB
*TST
*WAI
DDR
CMR

A
ARWV  ARBwave

B
BSWV  BASIC_WAVE
BTWV  BURSTWAVE
BUZZ  BUZZER

C
CHDR  COMM_HEADER
COUP  COUPLING

F
FCNT  FREQCOUNTER

I
IVNT  INVERT

L
LAGG  LANGUAGE

M
MDWV  MODULATEWAVE

N
NBFM  NUMBER_FORMAT

O
2 Programming Demos

2.1 Visual C++ Programming Demo

The program used in this demo: Microsoft Visual Studio 2003
The functions realized in this demo: use the NI-VISA to control the device with USBTMC or TCP/IP access to do a write or read operation.

1. Open Visual Studio: create a new VC++ win32 console project.
2. Set the project environment to use the NI-VISA lib, there are two ways to use the NI-VISA: static way and automatic way.
   2.1 static way:
      Find visa.h, visatype.h and visa32.lib files in NI-VISA install path. Copy them to your project, and add them into the project. In C++ source file, add the following two lines:
      #include "visa.h"
      #pragma comment (lib,"visa32.lib")
   2.2 automatic way:
      Let the head file include the NI-VISA install path. We can set the path
like: C:\Program Files\IVI Foundation\VISA\WinNT\include. Set this path to Project---Properties---C/C++---General---Additional Include Directories. See the picture below.

Set the lib path and file:

1) Set the lib path:

We can set the path: C:\Program Files\IVI Foundation\VISA\WinNT\lib\msc. The path is your NI-VISA install path. Set this path to Project---Properties---linker---general---Additional Library Directories. See the picture below.
2) Set the lib file:

Project---Properties---Linker---Command Line---Additional Options: visa32.lib. See the picture below.

Add the visa.h file into the project source file (xxx.cpp):
#include <visa.h>

3. Add your codes:
   3.1 Include the header files:
       #include "visa.h"
       #pragma comment(lib,"visa32.lib")  // static way

       // #include <visa.h>    // automatic way

       #include <stdlib.h>
       #include <stdio.h>
       #include <string.h>

   3.2 USBTMC access code:
       Write a function Usbtmc_test().
       int Usbtmc_test()
       {
         ViSession defaultRM;
         ViSession instr;
         ViUInt32 numInstrs;
         ViFindList findList;
         ViUInt32 retCount;
         ViUInt32 writeCount;
         ViStatus status;
         char instrResourceString[VI_FIND_BUFLEN];
         unsigned char buffer[100];
         char stringinput[512];
         int i;

         /* First we must call viOpenDefaultRM to get the manager */
         * handle. We will store this handle in defaultRM.
         */
         status = viOpenDefaultRM (&defaultRM);
         if (status < VI_SUCCESS)
         {
           printf("Could not open a session to the VISA Resource
                    Manager!\n");
           return status;
         }

         /* Find all the USBTMC VISA resources in our system and store the */
         * number of resources in the system in numInstrs. */
         status = viFindRsrc (defaultRM, "USB?*INSTR", &findList,
                            &numInstrs, instrResourceString);
         if (status < VI_SUCCESS)
         {
           }
printf("An error occurred while finding resources.\nHit enter to continue.");
fflush(stdin);
getchar();
viClose(defaultRM);
return status;
}

for(i=0; i<numInstrs; i++)
{
  if (i > 0)
    viFindNext(findList, instrResourceString);
  status = viOpen(defaultRM, instrResourceString, VI_NULL, VI_NULL, &instr);
  if (status < VI_SUCCESS)
  {
    printf("Cannot open a session to the device %d.\n", i+1);
    continue;
  }
  /* * At this point we have opened a session to the USBTMC instrument. We will use the viPrintf function to send the device the string "IDN?", asking for the device's identification.
   */
  char * cmmand="IDN?\n";
  status = viPrintf (instr, cmmand);
  if (status < VI_SUCCESS)
  {
    printf("Error writing to the device %d.\n", i+1);
    status = viClose (instr);
    continue;
  }
  /** Now we will attempt to read back a response from the device to the identification query that was sent. We will use the viScanf function to acquire the data.
   * After the data has been read the response is displayed.*/
  status = viScanf(instr, "%t", buffer);
  if (status < VI_SUCCESS)
  {
    printf("Error reading a response from the device %d.\n", i+1);
  }
{  
    printf("\nDevice %d: %*s\\n", i+1, retCount, buffer);  
}
status = viClose (instr);
}

/** Now we will close the session to the instrument using viClose. This operation frees all the system resources. */
status = viClose (defaultRM);
return 0;
}

3.3 TCP/IP access code:

Write a function TCP_IP_Test(char* pIP).

int TCP_IP_Test (char* pIP)
{
    char outputBuffer[VI_FIND_BUFLEN];
    ViSession defaultRM, instr;
    ViStatus status;
    ViUInt32 count;
    ViUInt16 portNo;
    /* First we will need to open the default resource manager. */
    status = viOpenDefaultRM (&defaultRM);
    if (status < VI_SUCCESS)
    {
        printf("Could not open a session to the VISA Resource Manager!\\n");
    }

    /* Now we will open a session via TCP/IP device */
    char head[256] = "TCP/IP0::";
    char tail[] = "::INSTR";
    char resource [256];
    strcat(head,pIP);
    strcat(head,tail);
    status = viOpen (defaultRM, head, VI_LOAD_CONFIG, VI_NULL, &instr);
    if (status < VI_SUCCESS)
    {
        printf("An error occurred opening the session\\n");
        viClose(defaultRM);
    }
    status = viPrintf(instr, "+idn?\\n");
    status = viSscanf(instr, "%t", outputBuffer);
    if (status < VI_SUCCESS)
3.4 main access code:

```c
int _tmain(int argc, _TCHAR* argv[])
{
    printf("please select the connect type , input 1 for usbtmc, input 2 for tcp/ip:");
    fflush(stdin);
    int inputchar = getchar();

    if(inputchar == 49)
    {
        Usbtmc_test();
    }
    else if(inputchar == 50)
    {
        printf("please input tcp/ip address: ");
        char ip[256];
        fflush(stdin);
        gets(ip);
        TCP_IP_Test(ip);
    }
    printf("Hit enter to continue.");
    fflush(stdin);
    getchar();
    return 0;
}
```

4 Run the demo and get result:

Save, compile and run the project. When the instrument connects to the PC correctly, you can choose USBTMC(1) or TCP/IP(2) to connect the instrument.